

Solving Equations

Suppose

$$f : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

Consider

$$f(x) = 0$$

Typical algorithms

Newton's method:

fast, but

can diverge

may try to evaluate $f(x)$ where it does not exist

Homotopy method:

reliable, but

slow

Alternative: Reformulate as an optimization problem

$$\text{Min}_x 1$$

$$\text{s.t. } f(x) = 0$$

Advantages

- **Variety of solvers**

Can use KNITRO, CONOPT, Filter, SNOPT, NPSOL, etc

- **Can impose constraints**

- **Impose domain conditions**

Suppose $f(x)$ is not defined for $x \leq 0$. Then solve

$$\text{Min}_x \quad 1$$

$$\text{s.t.} \quad \begin{aligned} f(x) &= 0 \\ x &\geq \epsilon \end{aligned}$$

for some small $\epsilon > 0$. Can't use $x \geq 0$ because then solver may consider some $x_i = 0$.

■ **Use auxiliary information about solution**

Suppose you know that the solution to $f(x)=0$ satisfies $a < x < b$ (a and b are vectors). We can use that information in

$$\text{Min}_x \quad 1$$

$$\text{s.t.} \quad \begin{aligned} f(x) &= 0 \\ a &\leq x \leq b \end{aligned}$$

More generally, if we know that $a \leq g(x) \leq b$, for some a , b , and g , then solve

$$\text{Min}_x \quad 1$$

$$\text{s.t.} \quad \begin{aligned} f(x) &= 0 \\ a &\leq g(x) \leq b \end{aligned}$$

- **Stabilize algorithm with L_2 penalty**

Suppose that the Jacobian of f is nearly singular near the solution. Then, the following quadratic penalty formulation stabilizes the algorithm:

$$\text{Min}_x \quad \|x\|_2^2$$

$$\text{s.t.} \quad f(x) = 0$$

where P is some penalty parameter, preferably small.

- **Stabilize algorithm with L_1 penalty**

An L_1 penalty might also help

$$\text{Min}_x \quad \|x\|_1$$

$$\text{s.t.} \quad f(x) = 0$$

where P is some penalty parameter, preferably small. (More later about how to do this.)

- **Stabilize via relaxation**

We can instead try to find something that nearly solves the equations:

$$\text{Min}_x \quad \|\lambda\|_1$$

$$\text{s.t.} \quad -\lambda_i \leq f(x) \leq \lambda_i$$

$$\lambda_i \geq 0$$

This will give you something instead of just saying “Can’t find a solution”

- **Find multiple solutions**

If there are many solutions, one could resolve the following problem several times for different π parameters:

$$\text{Min}_x \quad \pi \cdot x$$

$$\text{s.t.} \quad f(x) = 0$$

This will go after solutions on the boundary of the set of solutions.

The following will go after the solution closest to some chosen x_0 :

$$\text{Min}_x \quad \|x_0 - x\|_2^2$$

$$\text{s.t.} \quad f(x) = 0$$