Baseline Model

Structural Break

Conclusion O

Harold Zurcher and Paul Volcker— The Minutes of a Meeting That Never Was

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Harold Zurcher (1926—2020)

Maintenance manager at Madison (Wisconsin) Metropolitan Bus Company from 1955 to 1993



Paul Volcker (1927—2019)

Chairman of the United States Federal Reserve System from 1979 to 1987

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Outline

- The discount factor in DDCMs is considered to be hard to estimate due to its alleged **"poor identification"** (Rust, 1987; Aguirregabiria and Mira, 2010, and others)
- We propose a new method to *systematically* address this problem using **homotopy path continuation**
- In the "bus engine replacement model" of Rust (1987), we find—against common belief—the discount factor to be **well identified**, and *significantly* **larger than 1**
- Since discount factors greater than one are *unpopular*, we use a **natural experiment** to validate this finding:
 - Volcker's appointment curbed inflation (and negative *real* interest rates), happening in the middle of our sample
 - We add a **structural break** in Zurcher's discounting, finding that the *change* of the discount factor itself as well as the estimated *timing* strongly support our estimate

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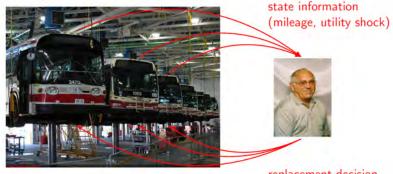
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The Bus Engine Replacement Model (Rust, 1987)

John Rust: *Optimal replacement of GMC bus engines: An empirical model of Harold Zurcher.* Econometrica, 1987.



replacement decision

Rust (1987) pioneered the estimation of dynamic discrete choice models, with decisions based on dynamic programming (Bellman)

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Harold Zurcher's Discount Factor Puzzle

- Estimating Zurcher's valuation of the future
 - To value and compare payoff streams in the future, Zurcher must discount them to a common date. This is formalized by the discount factor, here: β.
 - Under certain conditions, β in DDCMs can be estimated
- Rust (1987) attempted to do so, but failed:

I was not able to precisely estimate the discount factor [...] if I treated β as a free parameter, the estimated information matrix was nearly singular, causing difficulties for the maximization algorithm.

However, he adds:

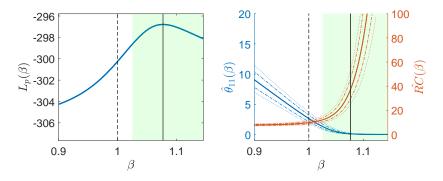
I did note a systematic tendency for the estimated value of β to be driven to 1. This curious behavior may be an artifact of computer round-off errors, or it could indicate a deeper result.

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A Resolution of the Puzzle?

- We address this problem using
 - our homotopy path continuation estimation approach
 - relative value iteration to account for divergence as $\beta
 ightarrow 1$
- We find the estimate for β
 - to be clearly identified
 - to be significantly larger than 1



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Estimation Results and Robustness

	Rust (1987)	Müller and Reich		
p	$\{1, 2, 3, 4\}$	$\{1, 2, 3, 4\}$	$\{1, 2, 3\}$ $\{4\}$	$ \{ 1, 2, 3 \} \\ \{ 4, 5, 7 \} \\ \{ 6, 8 \} $
\hat{eta}	0.9999	1.0768 [1.0245, ∞)	1.0467 [0.9897, 1.1042]	1.0283 [1.0073, 1.0476]
LL	-6,055.25	-6,051.79	-6,011.51	-11,097.82
p-value $(extsf{H}_0:eta=1)$	—	0.0086	0.1552	0.0092

On the "Acceptable Domain" of Discount Factors

• An editor:

Discount factors larger than one make little economic sense. I would interpret your results in that application as evidence for misspecification.

- Others accept $\beta \geq 1$ on various grounds:
 - Behavioral (Erdem and Keane, 1996):

The intertemporal factor is usually assumed to be between 0 and 1 because it is assumed to be 1 / (1 + interest rate) although behaviorally this does not have to hold.

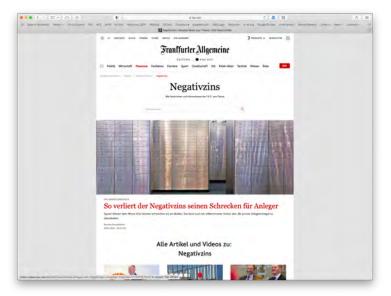
- Infinite horizon dynamic optimization problems can be viewed approximations of finite horizon problems (Morton and Wecker, 1977), justifying relative value iteration
- Kocherlakota (1990) theoretically treats discount factors greater than one in macro-economic growth models; Heaton (1995) estimates them
- Economic definition: **Negative interest rates** imply discount factors greater than one

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Negative Interest Rates are Real



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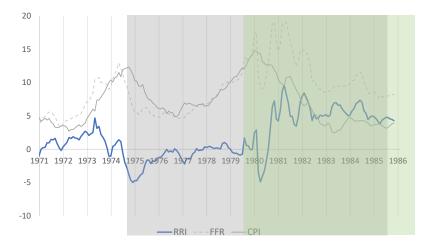
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Paul Volcker

- In July 1979, upon fears of a recession and inflation of about 12% in the United States, President Jimmy Carter nominates Paul Volcker as new Chairman of the Federal Reserve
- In the Congressional hearning, Volcker testifies:

the American people have, I suspect, become convinced as never before that inflation is here to stay and that it may rise. That affects activity; it affects the way they invest; it affects what they buy; it affects what they do. It makes our job more difficult. [...] And I hope [...] that we can get that psychology turned around through persistence and disciplined policies ntroduction Baseline Model Structural Break Conclusion

Macro-Economic Realities in the 1970ies and 80ies



Rate of real interest (RRI), federal funds rate (FFP), consumer price index (CPI); source: Fed St.Louis

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A Natural Experiment

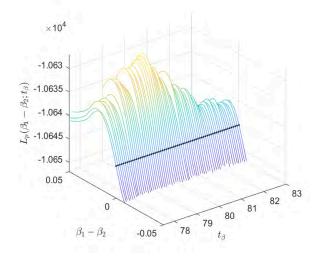
- Conditions for a natural experiment
 - Volcker's announcement and implementation of his new monetary policy created a disruptive change in economic environment in 1979 and 1980.
 - The Zurcher data set sampling window is from 1974 to 1985
- Setup for a structural break model
 - Intuition: If there is a qualitative link between Zurcher's discounting and the real interest rates, we expect a reduction in discounting (due to a rise in real interest rates) shortly after Volcker's announcement.
 - Introduce an **unanticipated structural break** in Zurcher's discounting at an **unknown date**, t_{β} .
 - For $t < t_{eta}$, Harold Zurcher discounts with eta_1 from t up to ∞
 - For $t \geq t_{eta}$, Harold Zurcher discounts with eta_2 from t up to ∞
 - Test: $H_0: \beta_1 = \beta_2$ against $H_0: \beta_1 > \beta_2$ (or two-sided)

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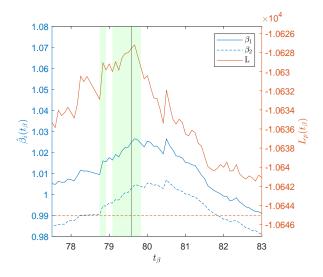
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Tracing $\Delta \beta = \beta_1 - \beta_2$



Introduction Baseline Model 00 0000000 Structural Break

The "Meeting" of Harold Zurcher and Paul Volcker



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p	$\{1,2,3\},\{4,5,7\},\{6,8\}$
t_eta	Sept 1979
β_1	[Oct 1978, Dec 1978] ∪ [Feb 1979, Nov 1979] 1.0269
β_2	[1.0045, 1.0465] 1.0047
	[0.9852, 1.0197]
LL	-10,627.1853
p-value	$2.19\cdot 10^{-9}$
$(H_0:\beta_1=\beta_2)$ p-value	$6.55 \cdot 10^{-10}$
$(H_0:\beta_1=\beta_2=1)$	

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Conclusion

Conclusions and Outlook

- Methodological contribution
 - Method to systematically estimate models even in the presence of non-identified or poorly identified parameters
- Empirical contribution
 - Contrary to common belief, the discount factor in Rust (1987) is well identified and larger than 1
 - We find strong a strong indication for a qualitative link between the discount factor and the real interest rates as both the time of the structural break and the change of the discount rate agree
- Current work and outlook
 - Treat discounting as a *state* (exogenous, unobserved, serially correlated), and estimate the model using recursive likelihood function integration (RLI; Reich, 2018)
 - Apply this approach to model and data with *many* decision makers

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Rust (1987) 0000

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Rust (1987) ●○○○

Rust (1987): Utility Function

• Agent's utility + shock for the single period payoff

$$u(x_t, d_t; heta_{11}, \mathsf{RC}) + \epsilon_t(d_t) = egin{cases} -c(x_t, heta_{11}) + \epsilon_t(0) & ext{if } d_t = 0 \ -RC + \epsilon_t(1) & ext{if } d_t = 1 \end{cases}$$

- $d_t = 0$: performing regular maintenance
- $d_t = 1$: replacing the engine
- State variables
 - x_t mileage state
 - ϵ i.i.d. gumbel utility shock (only observed by agent)

Parameters

- θ_{11} regular maintenance cost parameter
- RC replacement cost parameter

Value Function - Dynamic Programming

Objective The agent wants to maximize his expected discounted utility over an **infinite horizon**.

$$V_{\theta,\beta}(x_t,\epsilon_t) = \max_{D(x_t)\in\mathcal{D}} \mathbb{E}\left[\sum_{j=t}^{\infty} \beta^{j-t} \left(u(x_j, D(x_j); \theta_1, \mathsf{RC}) + \epsilon(D(x_j))\right) \big| x_t\right]$$

where $\theta \equiv (\mathsf{RC}, \theta_1)$ and $D(\cdot)$ denotes the policy function.

 \land For $\beta \rightarrow 1$, we have $V \rightarrow -\infty$

Bellman V is the unique solution to the Bellman equation

$$V_{\theta,\beta}(x,\epsilon) = \max_{d \in \{0,1\}} [u(x,d,\theta_1) + \epsilon(d) + \beta \mathbb{E}[V_{\theta,\beta}(x',\epsilon')|x,d]] =: T(V),$$

where x' and ϵ' denote the next period state variables.

Dynamic Programming with $\beta>1$

- Recall We can solve for the optimal value function by solving the fixed-point equation $V = T_{\theta,\beta}(V)$.
 - Note Even though, the value function $V \to \infty$, the difference between the value at different states might be finite
 - We solve for the **relative value function** $h = V V_1$ by

$$h = T_{\theta,\beta}(h) - T_{\theta,\beta}(h)_1$$

 For β ∈ ℝ⁺, Morton & Wecker (1977) have derived a set of conditions under which the resulting policy is optimal

Intuition: Relative values denote the *difference in total* expected value when starting from state x opposed to starting from state 1.

Structural Estimation

- Data \sim 15'000 observations of the state and control variables from 1974 to 1985.
- Objective Identify the most likely values for the parameters $\theta = (\theta_{11}, \text{RC})$ and β given the observed data.
- Approach Simultaneously solve the likelihood and fixed-point problem

$$egin{aligned} & heta^*, eta^* = rg\max_{ heta,eta} L(h, heta,eta;\{x_t,d_t\}) \ & \ h = T_{ heta,eta}(h) - T_{ heta,eta}(h)_1|_{ heta= heta^*,eta=eta^*} \end{aligned}$$

 $T(\cdot)$ denotes the Bellman operator, h the relative values

• Two popular solution methods are NFXP Rust (1987) and MPEC by Su and Judd (2012)

Rust (1987) 0000 Method •000

MPEC

• Su and Judd (2012) formulate the structural estimation as constrained optimization

$$\max_{\substack{(h,\theta,\beta)}} L(\theta,\beta,h;\{x_t,d_t\}),$$

s.t. $h = T_{\theta,\beta}(h) - T_{\theta,\beta}(h)_1,$

with $\theta \in \mathbb{R}^2$, $\beta \in \mathbb{R}_+$, and $h \in \mathbb{R}^{90}$.

β is "poorly identified" if the likelihood is (almost) flat in β. Numerically, its Hessian becomes (nearly) singular ⇒ hard to estimate ⇒ "calibrated" to some notion of the interest rate.

Rust (1987)

Method 0000

PMPEC

• We propose to formulate the structural estimation as parameterized MPEC:

$$\begin{split} L_{\rho}(\beta) &= \max_{(h,\theta,\beta)} L(\theta,\beta,h;\{x_t,d_t\}),\\ \text{s.t. } h &= T_{\theta,\beta}(h) - T_{\theta,\beta}(h)_1, \end{split}$$
 with $\theta \in \mathbb{R}^2$, $\beta \in \mathbb{R}_+$, and $h \in \mathbb{R}^{90}$.

• $L_p(\beta)$ denotes augmented profile likelihood

First-Order Necessary Optimality Conditions

• Its Lagrangian ${\cal L}$ is defined as

$$\mathcal{L}(\theta, h, \mu; \beta) = \mathcal{L}(\theta, h; \beta) - \sum_{i} \mu_{i} (h - T_{\theta, \beta}(h) + T_{\theta, \beta}(h)_{1})$$

 First-order necessary conditions form a system of equations parameterized in β:

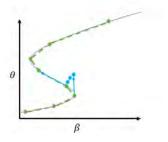
$$\nabla_{(\theta,h,\mu)} \mathcal{L}(\theta^*, h^*, \mu^*; \beta) = 0.$$
(1)

• We are interested in the solution manifold of the parametrized FOC (profile likelihood as implicit function)

$$c \equiv \{(\beta, \theta, h, \mu) : \nabla_{\theta, h, \mu} \mathcal{L}(\beta, \theta, h, \mu) = 0\}$$

Predictor-Corrector Homotopy Continuation

- Trace the one-dimensional solution manifold by *homotopy path continuation*.
- Predictor-Corrector in a nutshell



• Software: HOMPACK90 (Watson et al., 1997) with a self-written Matlab interface