

# Solving ill-conditioned problems via Proximal Point method

Suppose you have an objective which has a singular Hessian at the minimum (or maximum).

Economic examples: Flat top of likelihood hill, flat bottom to a moments criterion minimum

Newton's method may not properly converge for such problems

Round-off errors could cause convergence far from true solution

Any convergence will be slow.

### Simple example

```
In[647]:= a = 5; wgt = .; xold = .; yold = .
```

Suppose your objective is

```
In[648]:= obj = (x + y - a)^4
```

```
Out[648]= (-5 + x + y)^4
```

There are multiple minima: any  $(x,y)$  such that  $x+y=5$ .

You can identify  $x+y$  but not  $(x,y)$

```
In[649]:= FindMinimum[obj, {x, 2}, {y, 2}]
```

```
Out[649]= {1. × 10-16, {x → 2.49995, y → 2.49995}}
```

This problem is so trivial and FindMinimum good enough that we get a solution. We stay with simple case to show basic idea.

So, suppose things did not go well.

## Proximal Point method

Construct a penalty function

(xold, yold) is most recent guess

the penalty function is a quadratic penalty for choosing (x,y) different from (xold, yold)

```
In[650]:= pen = (x - xold)2 + (y - yold)2
```

```
Out[650]= (x - xold)2 + (y - yold)2
```

Create a new objective function

```
In[651]:= objProx = obj + wgt pen
```

```
Out[651]= (-5 + x + y)4 + wgt ((x - xold)2 + (y - yold)2)
```

objProx wants to minimize obj but imposes a cost for straying from (xold, yold)

We need to set the weight, and initial values for (xold, yold)

```
In[655]:= wgt = 0.1;
```

```
xold = yold = 10;
```

```
In[657]:= objProx
```

```
Out[657]= 0.1 ((-10 + x)2 + (-10 + y)2) + (-5 + x + y)4
```

## Solve

```
In[658]:= FindMinimum[objProx, {x, 2}, {y, 2}][[2]]
```

```
Out[658]= {x → 2.85478, y → 2.85478}
```

We get a solution. Let's reset (xold, yold) and try again.

```
In[659]:= {xold, yold} = {x, y} /. %
```

```
Out[659]= {2.85478, 2.85478}
```

```
In[660]:= FindMinimum[objProx, {x, 2}, {y, 2}][[2]]
```

```
Out[660]= {x → 2.61451, y → 2.61451}
```

## Repeat

```
In[661]:= {xold, yold} = {x, y} /. %
```

```
Out[661]= {2.61451, 2.61451}
```

```
In[662]:= FindMinimum[objProx, {x, 2}, {y, 2}][[2]]
```

```
Out[662]= {x → 2.56681, y → 2.56681}
```

```
In[663]:= {xold, yold} = {x, y} /. %
```

```
Out[663]= {2.56681, 2.56681}
```

```
In[664]:= FindMinimum[objProx, {x, 2}, {y, 2}][[2]]
```

```
Out[664]= {x → 2.54853, y → 2.54853}
```

```
In[665]:= {xold, yold} = {x, y} /. %
```

```
Out[665]= {2.54853, 2.54853}
```

We now seemed to have become stuck. Remember that the weight is 0.1.  
Let's reduce the weight on the penalty

```
In[666]:= wgt = 0.001;
```

```
In[667]:= FindMinimum[objProx, {x, 2}, {y, 2}][[2]]
```

```
Out[667]:= {x → 2.51304, y → 2.51304}
```

Progress! Let's repeat this a few times

```
In[668]:= {xold, yold} = {x, y} /. %
```

```
Out[668]:= {2.51304, 2.51304}
```

```
In[669]:= FindMinimum[objProx, {x, 2}, {y, 2}][[2]]
```

```
Out[669]:= {x → 2.50716, y → 2.50716}
```

```
In[670]:= {xold, yold} = {x, y} /. %
```

```
Out[670]:= {2.50716, 2.50716}
```

```
In[671]:= FindMinimum[objProx, {x, 2}, {y, 2}][[2]]
```

```
Out[671]:= {x → 2.50507, y → 2.50507}
```

```
In[672]:= {xold, yold} = {x, y} /. %
```

```
Out[672]:= {2.50507, 2.50507}
```

We could reduce the penalty weight further and get closer to some  $(x, y)$  such that  $x+y=5$ , but let's stop here.

What was the benefit of doing this?

- Each step in the optimization problem was well-conditioned

- Each step will converge quadratically to the solution of the penalized objective

- You get arbitrarily close to some solution

- You still cannot identify  $(x, y)$  but you can find a point that solves the problem

Identification

- Economists are obsessed with identification

- Why? No good reason.

My opinion: write down the model you think is valid and then let the computer tell you if you have identification.