

Solving Equations

Suppose $f : R^n \rightarrow R^n$. Consider the equation

$$f(x) = 0$$

Typical algorithms

Newton's method:

- fast, but

- can diverge

- may try to evaluate $f(x)$ where it does not exist

Homotopy method:

- reliable, but

- slow

Alternative: Reformulate as an optimization problem

$$\begin{array}{ll} \text{Min}_x & 1 \\ \text{s.t.} & f(x) = 0 \end{array}$$

Advantages

Variety of solvers

Can use KNITRO, CONOPT, Filter, SNOPT, NPSOL, etc

Can impose constraints

Impose domain conditions

Suppose $f(x)$ is not defined for $x \leq 0$. Then solve

$$\begin{array}{ll} \text{Min}_x & 1 \\ \text{s.t.} & f(x) = 0 \\ & x \geq \epsilon \end{array}$$

for some small $\epsilon > 0$. Can't use $x \geq 0$ because then solver may consider some $x_i = 0$.

Use auxiliary information about solution

Suppose you know that the solution to $f(x)=0$ satisfies $a < x < b$ (a and b are vectors). We can use that information in

$$\begin{array}{ll} \text{Min}_x & 1 \\ \text{s.t.} & f(x) = 0 \\ & a \leq x \leq b \end{array}$$

More generally, if we know that $a \leq g(x) \leq b$, for some a , b , and g , then solve

$$\begin{array}{ll} \text{Min}_x & 1 \\ \text{s.t.} & f(x) = 0 \\ & a \leq g(x) \leq b \end{array}$$

Stabilize algorithm with L_2 penalty

Suppose that the Jacobian of f is nearly singular near the solution. Then, the following quadratic penalty formulation stabilizes the algorithm:

$$\begin{array}{ll} \text{Min}_x & \|x\|_2^2 \\ \text{s.t.} & f(x) = 0 \end{array}$$

where P is some penalty parameter, preferably small.

Stabilize algorithm with L_1 penalty

An L_1 penalty might also help

$$\begin{array}{ll} \text{Min}_x & \|x\|_1 \\ \text{s.t.} & f(x) = 0 \end{array}$$

where P is some penalty parameter, preferably small. (More later about how to do this.)

Stabilize via relaxation

We can instead try to find something that nearly solves the equations:

$$\begin{array}{ll} \text{Min}_{x,\lambda} & \|\lambda\|_1 \\ \text{s.t.} & -\lambda_i \leq f(x) \leq \lambda_i \\ & \lambda_i \geq 0 \end{array}$$

This will give you something instead of just saying “Can’t find a solution”

You could use the max norm

$$\begin{array}{ll} \text{Min}_{x,\lambda} & \|\lambda\|_\infty \\ \text{s.t.} & -\lambda_i \leq f(x) \leq \lambda_i \\ & \lambda_i \geq 0 \end{array}$$

Find multiple solutions

If there are many solutions, one could resolve the following problem several times for different π parameters:

$$\begin{array}{ll} \text{Min}_x & \pi \cdot x \\ \text{s.t.} & f(x) = 0 \end{array}$$

This will go after solutions on the boundary of the set of solutions.

The following will go after the solution closest to some chosen x_0 :

$$\begin{array}{ll} \text{Min}_x & \|x_0 - x\|_2^2 \\ \text{s.t.} & f(x) = 0 \end{array}$$